

# Assignment 11 Solutions

(1)

Loventz-invariance of Ampere's law

$$\vec{\nabla} \times \vec{B} - \frac{1}{c^2} \frac{\partial \vec{E}}{\partial t} = \mu_0 \vec{J}$$

velocity of primed frame relative to unprimed frame:

$$\vec{V} = v \hat{x}$$

field transformation:

$$E_x' = E_x \quad E_y' = \gamma(E_y - v B_z) \quad E_z' = \gamma(E_z + v B_y)$$

$$B_x' = B_x \quad B_y' = \gamma(B_y + \frac{v}{c^2} E_z) \quad B_z' = \gamma(B_z - \frac{v}{c^2} E_y)$$

derivative transformation:

$$\frac{\partial}{\partial t'} = \gamma \frac{\partial}{\partial t} + \gamma v \frac{\partial}{\partial x}$$

$$\frac{\partial}{\partial x'} = \gamma \frac{\partial}{\partial x} + \gamma \frac{v}{c^2} \frac{\partial}{\partial t}$$

$$\frac{\partial}{\partial y'} = \frac{\partial}{\partial y}$$

$$\frac{\partial}{\partial z'} = \frac{\partial}{\partial z}$$

charge-current density trans. : (2)

$$\rho' = \gamma(\rho - \frac{v}{c^2} j_x)$$

$$j_x' = \gamma(j_x - v\rho)$$

$$j_y' = j_y$$

$$j_z' = j_z$$

x-component :

$$\frac{\partial B_z'}{\partial y'} - \frac{\partial B_y'}{\partial z'} - \frac{1}{c^2} \frac{\partial E_x'}{\partial t'} \stackrel{?}{=} \mu_0 j_x'$$

$$\gamma\left(\frac{\partial B_z}{\partial y} - \frac{v}{c^2} \frac{\partial E_y}{\partial y}\right) - \gamma\left(\frac{\partial B_y}{\partial z} + \frac{v}{c^2} \frac{\partial E_z}{\partial z}\right)$$

$$- \frac{1}{c^2} (\gamma \frac{\partial}{\partial t} + \gamma v \frac{\partial}{\partial x}) E_x \stackrel{?}{=} \mu_0 \gamma (j_x - v\rho)$$

$$\underbrace{\gamma\left(\frac{\partial B_z}{\partial y} - \frac{\partial B_y}{\partial z} - \frac{1}{c^2} \frac{\partial E_x}{\partial t}\right)}_{\mu_0 j_x \checkmark} - \underbrace{\gamma \frac{v}{c^2} \vec{\nabla} \cdot \vec{E}}_{\substack{\rho/\epsilon_0 \\ -\mu_0 \gamma v \rho \checkmark}} \stackrel{!}{=} \mu_0 \gamma j_x - \mu_0 \gamma v \rho$$

y-component:

(3)

$$\frac{\partial B'_x}{\partial z'} - \frac{\partial B'_z}{\partial x'} - \frac{1}{c^2} \frac{\partial E'_y}{\partial t'} \stackrel{?}{=} \mu_0 j'_y$$

$$\frac{\partial B_x}{\partial z} - \gamma^2 \left( \frac{\partial}{\partial x} + \frac{v}{c^2} \frac{\partial}{\partial t} \right) (B_z - \frac{v}{c^2} E_y)$$

$$- \frac{1}{c^2} \gamma^2 \left( \frac{\partial}{\partial t} + v \frac{\partial}{\partial x} \right) (E_y - v B_z) \stackrel{?}{=} \mu_0 j$$

Terms marked (1) and (2) cancel.

$$\frac{\partial B_x}{\partial z} - \underbrace{\gamma^2 \left( 1 - \frac{v^2}{c^2} \right)}_1 \frac{\partial B_z}{\partial x} - \underbrace{\frac{\gamma^2}{c^2} \left( 1 - \frac{v^2}{c^2} \right)}_{1/c^2} \frac{\partial E_y}{\partial t} \stackrel{!}{=} \mu_0 j_y$$

Since the z-component is also perpendicular to  $\vec{v}$ , it works out in the same way as the y-component.

Gauss law :

$$\vec{\nabla}' \cdot \vec{E}' \stackrel{?}{=} \rho' / \epsilon_0$$

$$\gamma \left( \frac{\partial}{\partial x} + \frac{v}{c^2} \frac{\partial}{\partial t} \right) E_x + \frac{\partial}{\partial y} \gamma (E_y - v B_z)$$

$$+ \frac{\partial}{\partial z} \gamma (E_z + v B_y) \stackrel{?}{=} \frac{1}{\epsilon_0} \gamma \left( \rho - \frac{v}{c^2} j_x \right)$$

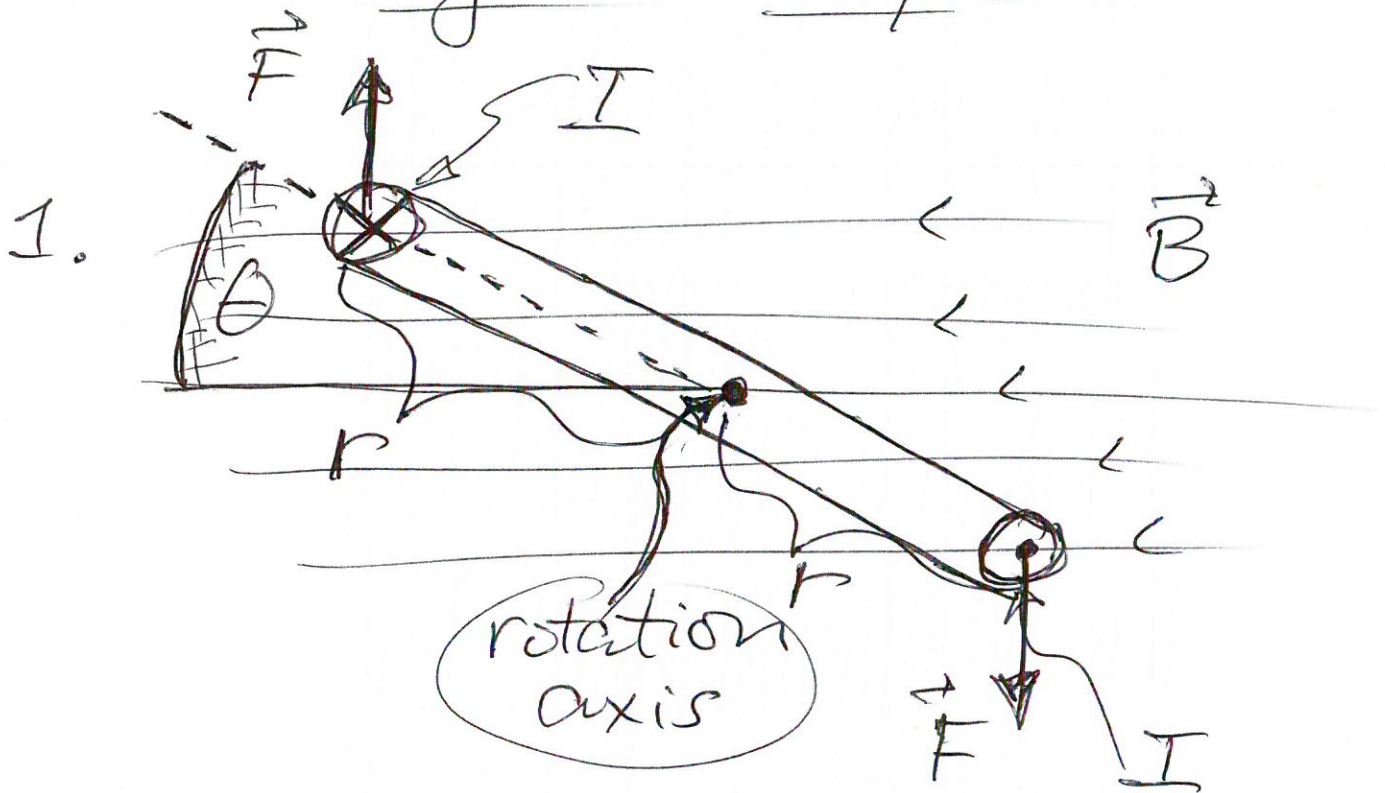
$$\underbrace{\gamma \vec{\nabla} \cdot \vec{E}}_{\rho / \epsilon_0} = \gamma v \left( \frac{\partial B_z}{\partial y} - \frac{\partial B_y}{\partial z} - \frac{1}{c^2} \frac{\partial E_x}{\partial t} \right)$$

$$\mu_0 j_x = \frac{1}{\epsilon_0 c^2} j_x$$

$$\stackrel{!}{=} \gamma \frac{\rho}{\epsilon_0} - \gamma v \frac{1}{\epsilon_0 c^2} j_x$$

energy balance with  
magnetic torque

(4)



Only  $\vec{F} = IL\hat{L} \times \vec{B}$  on two sides of length  $L$  is shown.

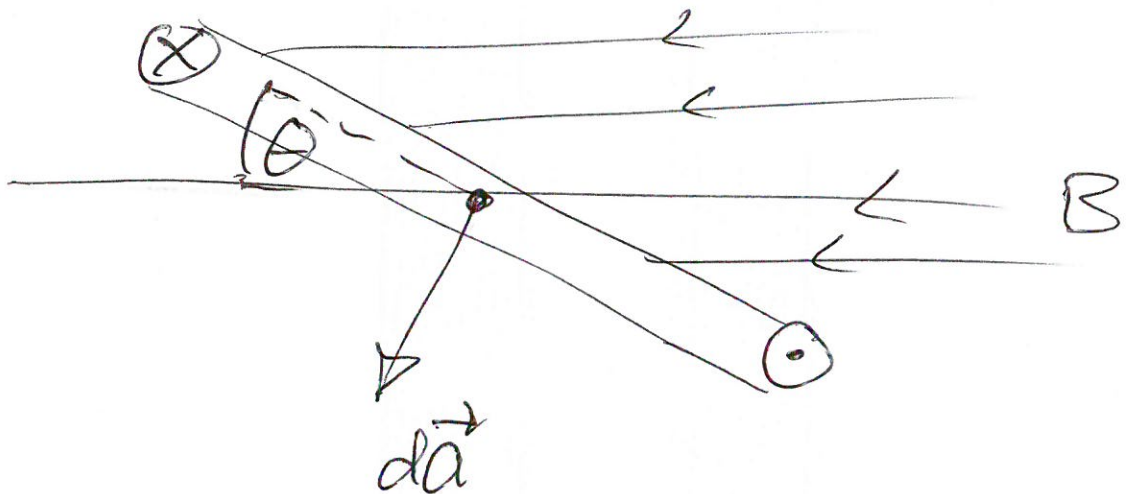
$d\vec{F}$  on other sides is always parallel to rotation axis, so does not produce torque about that axis

$$2. \tau = 2 \times F \cdot \underbrace{r \cos \theta}_{\text{"lever arm"}}$$

$$= 2IBLr \cos \theta$$

$$P_{\text{rot}} = \omega \tau = 2\omega IBLr \cos \theta$$

3.



$$\vec{B} \cdot d\vec{a} = B |d\vec{a}| \underbrace{\cos(\pi/2 - \theta)}_{\sin \theta}$$

$$\Phi_B(\theta) = (B \sin \theta) \cdot (2rL)$$

$$\mathcal{E}_F = -\dot{\Phi}_B = -(B \cos \theta) \omega (2rL)$$

Current in the wire loop would lose energy at rate  $I\mathcal{E}_F$ , if the battery did not perform extra work to make up for this loss. Notice that

$$-I\mathcal{E}_F = 2\omega I B L r \cos\theta$$

$$= \omega\tau = P_{\text{rot}},$$

so the extra work matches exactly the work that goes into increasing the rotational mechanical energy.