## origins

- splitting method for PDEs

Douglas-Rachford (DR) splitting, 1956

- convex optimization
alternating direction method of multipliers (ADMM), 1974
- phase retrieval

Fienup's hybrid input-output (HIO), 1982

## Douglas-Rachford splitting

$$
\begin{aligned}
& \text { Douglas, Jim, Jr., and Henry H. Rachford Jr. } \\
& \text { "On the numerical solution of heat conduction } \\
& \text { problems in two and three space variables." } \\
& \text { Transactions of the American mathematical Society } \\
& 82.2 \text { (1956): 421-439. (1452 citations) }
\end{aligned}
$$

## Idea:

"Split" equations into two sets, one involving only $x$-derivatives, the other only $y$-derivatives, and devise an iteration scheme that solves the 2D problem where in each step you only need to solve 1D problems.

## ADMM

## Also motivated by numerical solution of PDEs

(Dirichlet problem for the s-Laplacian operator)
R. Glowinski \& A. Marrocco
S. Boyd, N. Parikh, E. Chu, B. Peleato, and J. Eckstein
"Distributed Optimization and Statistical Learning via the Alternating Direction Method of Multipliers"
Foundations and Trends in Machine Learning, 3(1):1-122, 2011.
(6541 citations)
online:
https://web.stanford.edu/~boyd/papers/admm distr stats.html

## ADMM variables

$$
\begin{aligned}
p_{1}^{\prime} & =P_{1}\left(p_{2}-u\right) \\
u^{\prime} & =u+\alpha\left(p_{1}^{\prime}-p_{2}\right) \\
p_{2}^{\prime} & =P_{2}\left(p_{1}^{\prime}+u\right)
\end{aligned}
$$

$u=$ "accumulated constraint discrepancy"

$$
\begin{gathered}
\text { define } x=p_{2}-u, \quad \text { set } \alpha=1: \\
x^{\prime}=x+P_{2}\left(2 P_{1}(x)-x\right)-P_{1}(x)
\end{gathered}
$$

result: RRR with $\beta=1$

## hybrid input-output algorithm (HIO)

Fienup, James R.<br>"Phase retrieval algorithms: a comparison."<br>Applied optics 21.15 (1982): 2758-2769.

(4067 citations)

Still another method of choosing the next input which was investigated is a combination of the upper line of Eq. (43) with the lower line of Eq. (42):

$$
g_{k+1}(x)= \begin{cases}g_{k}^{\prime}(x), & x \nless \gamma,  \tag{44}\\ g_{k}(x)-\beta g_{k}^{\prime}(x), & x_{\varepsilon} \gamma .\end{cases}
$$

$g(x)$ : Fourier magnitude projection of $x$
$x \notin \gamma: x \in$ support

## difference map

$$
\begin{gathered}
\begin{array}{l}
\text { Elser, Veit } \\
\text { "Phase retrieval by iterated projections." } \\
\text { JOSA A } 20.1(2003): 40-55 .
\end{array} \\
x^{\prime}=x+\beta\left(P_{2}\left((1+\gamma) P_{1}(x)-\gamma x\right)-P_{1}\left((1-\gamma) P_{2}(x)+\gamma x\right)\right) \\
\gamma=1 / \beta
\end{gathered}
$$

"derived" from simple Ansatz and local fixed-point analysis

## Jonathan Borwein (1951-2016)


reflect-reflect-average: $\quad x^{\prime}=\frac{x+R_{2}\left(R_{1}(x)\right)}{2}$ reflect in constraint $i: \quad R_{i}(x)=2 P_{i}(x)-x$ relaxed-reflect-reflect $=$ RRR :

$$
\begin{aligned}
& x^{\prime}=(1-\beta / 2) x+(\beta / 2) R_{2}\left(R_{1}(x)\right) \\
& x^{\prime}=x+\beta\left(P_{2}\left(2 P_{1}(x)-x\right)-P_{1}(x)\right)
\end{aligned}
$$

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Dear Veit.
Do send my best to Steve.
In general for projection and reflection methods, especially in
the convex case, under-relaxation can improve convergence
theory while slowing things down.
I would be interested in knowing more about your examples where
it is helping?
Cheers, Jon
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Artacho, Francisco J. Aragón, and Jonathan M. Borwein.
"Global convergence of a non-convex Douglas-Rachford iteration."
Journal of Global Optimization 57.3 (2013): 753-769.

