Lecture 25: March 29
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### 25.1 Angle action variables

There is a special choice of variables we use for periodic motion. Since the motion always stays on a "surface" of constant $\mathcal{H}$, and for one degree of freedom these surfaces are contours in a two dimensional phase space, the constant $\mathcal{H}$ contours will be closed curves when the motion is periodic. The "action variable", traditionally written $I$, is defined as

$$
\begin{equation*}
2 \pi I(q, p)=\text { phase space area (action) enclosed by } \mathcal{H} \text { contour passing through }(q, p) \tag{25.1}
\end{equation*}
$$

This variable plays the role of the transformed momentum variable, denoted $P$ in previous lectures. By construction, $I$ is always non-negative and the Hamiltonian (for the new variables) is solely a function of $I$ :

$$
\begin{equation*}
\mathcal{H}^{\prime}=h(I) \tag{25.2}
\end{equation*}
$$

The transformed coordinate variable, that $I$ is conjugate to (and previously denoted $Q$ ), is written $\theta$ and called the "angle variable". We can define $\theta$ by a geometrical construction as follows. Draw a curve, starting at the point $\left(q_{0}, p_{0}\right)$ in phase space where $I=0$ (the center of all the contours), and crossing all the contours exactly once. Unless the contours have complicated shapes, a straight ray serves this purpose. This ray/curve defines $\theta=0$ everywhere in phase space. To define $\theta$ elsewhere, we use the phase-space area constancy property. Consider the annular region in the ( $q, p$ ) plane bounded by contours with action $I$ and $I+\Delta I$. The canonical transformation maps this annulus to a rectangular region in the $(\theta, I)$ plane bounded by $I, I+\Delta I, \theta=0$ and $\theta=2 \pi$. In order that equal areas of the annulus get mapped to equal areas in the rectangle, we define the angle variable as follows:

$$
\begin{equation*}
\theta(q, p) / 2 \pi=\text { fraction of the annulus area, measured clockwise from } \theta=0 \tag{25.3}
\end{equation*}
$$

Exercise: Sketch the $(q, p)$ and $(\theta, I)$ phase spaces side by side, showing some corresponding contours of constant $I$ (and constant $\mathcal{H}$ ). Locate points in the $(q, p)$ plane that correspond to $\theta=0$ and $\theta=\pi / 2$.

Hamilton's equations in the transformed variables are exceedingly simple:

$$
\begin{align*}
\dot{\theta} & =+\frac{\partial \mathcal{H}^{\prime}}{\partial I}=\frac{d h}{d I}  \tag{25.4}\\
\dot{I} & =-\frac{\partial \mathcal{H}^{\prime}}{\partial \theta}=0 \tag{25.5}
\end{align*}
$$

The second equation implies $I=I_{0}$ is constant - something we already new since $\mathcal{H}^{\prime}=h(I)$ will only be constant if $I$ is constant. The solution of the first equation is almost as simple:

$$
\begin{gather*}
\dot{\theta}=\left.\frac{d h}{d I}\right|_{I=I_{0}}=\omega_{0}=\mathrm{constant}  \tag{25.6}\\
\theta(t)=\omega_{0} t+\theta_{0} \tag{25.7}
\end{gather*}
$$

The periodicity of orbits is built into the topology of the $(\theta, I)$ phase space, as we declare the points $(0, I)$ and $(2 \pi, I)$ equivalent. In other words, the two sides of the semi-infinite rectangle are sewn together, topologically, into a cylinder.

A useful way to think about the transformed Hamiltonian (25.2) is in terms of its derivative. Let $T_{0}$ be the period of the motion when the action is $I_{0}$. By (25.7) we have $\omega_{0} T_{0}=2 \pi$, and therefore, using (25.6),

$$
\begin{equation*}
\left.\frac{d h}{d I}\right|_{I=I_{0}}=\frac{2 \pi}{T_{0}} \tag{25.8}
\end{equation*}
$$

### 25.1.1 Transforming the simple harmonic oscillator to angle action variables

Let's construct the actual transformation to angle-action variables for the simplest model of periodic motion: the harmonic oscillator. We will consider a pendulum where the length of the string $l$ may be varied over time. Since the canonical transformation in this case is time-dependent, we will eventually need the full machinery of generating functions (lecture 24) to work out the transformed Hamiltonian $\mathcal{H}^{\prime}$.

Assuming a massless string supporting a point mass $M$, the Lagrangian of the system is

$$
\begin{align*}
\mathcal{L}=T-V & =\frac{1}{2} M(l \dot{\phi})^{2}-M g l(1-\cos \phi)  \tag{25.9}\\
& \approx \frac{1}{2} M(l \dot{\phi})^{2}-\frac{1}{2} M g l \phi^{2} \tag{25.10}
\end{align*}
$$

where $\phi$ is the angle from the vertical, and we are interested only in small amplitude oscillations. To preserve continuity with the earlier notation, we make the replacement $\phi \rightarrow q$ for the coordinate and define
the conjugate momentum in the usual way:

$$
\begin{equation*}
p=\frac{\partial \mathcal{L}}{\partial \dot{q}}=M l^{2} \dot{q} . \tag{25.11}
\end{equation*}
$$

We write the resulting Hamiltonian in two ways,

$$
\begin{align*}
\mathcal{H}=p \dot{q}-\mathcal{L} & =\left(\frac{1}{2 M l^{2}}\right) p^{2}+\left(\frac{M g l}{2}\right) q^{2}  \tag{25.12}\\
& =\left(\frac{1}{2 M l^{2}}\right) p^{2}+\left(\frac{M \omega^{2} l^{2}}{2}\right) q^{2} \tag{25.13}
\end{align*}
$$

where

$$
\begin{equation*}
\omega=\sqrt{g / l} \tag{25.14}
\end{equation*}
$$

When we later study the effect of a time dependent length $l$ we will have to remember that this makes the frequency $\omega$ also time dependent.

Here is the generating function that will transform the $(q, p)$ phase space of the harmonic oscillator to the angle action $(\theta, I)$ phase space:

$$
\begin{equation*}
F(q, \theta, t)=\frac{1}{2} M \omega l^{2} q^{2} \cot \theta \tag{25.15}
\end{equation*}
$$

Note that the second argument of $F$ is occupied by $\theta$, our name for the transformed coordinate variable. The canonical transformation is determined by the following two equations:

$$
\begin{align*}
p & =+\frac{\partial F}{\partial q}=M \omega l^{2} q \cot \theta  \tag{25.16}\\
I & =-\frac{\partial F}{\partial \theta}=-\frac{1}{2} M \omega l^{2} q^{2}\left(\frac{-1}{\sin ^{2} \theta}\right) \tag{25.17}
\end{align*}
$$

Solving for $q$ in the second equation,

$$
\begin{equation*}
q=\sqrt{\frac{2 I}{M \omega l^{2}}} \sin \theta \tag{25.18}
\end{equation*}
$$

we see that the "angle variable" $\theta$ is not the same as the angle $q=\phi$ of the pendulum. Substituting this $q$ into the first equation, we obtain

$$
\begin{equation*}
p=\sqrt{2 I M \omega l^{2}} \cos \theta \tag{25.19}
\end{equation*}
$$

Finally, substituting these formulas expressing $(q, p)$ in terms of $(\theta, I)$ into the Hamiltonian (25.13), we obtain

$$
\begin{equation*}
\mathcal{H}^{\prime}(\theta, I, t)=\omega I+\frac{\partial F}{\partial t} . \tag{25.20}
\end{equation*}
$$

When the transformation is time-independent $(\partial F / \partial t=0)$ the transformed Hamiltonian is especially simple: a linear function of $I$. This should not be surprising because we know that the period (25.8) of the simple harmonic oscillator is a constant, independent of amplitude (enclosed action).

